

Semantics of Probabilistic Programming

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Most of the content is from “Semantics of Probabilistic Programming:
A Gentle Introduction” by Fredrik Dahlqvist, Alexandra Silva, and Dexter Kozen

Recap: Problem and Motivation

- Evaluate $P(Z | X)$ and related expectations
- Problem with exact methods
 - Curse of dimensionality
 - $P(Z | X)$ has a complex form making expectations analytically intractable

Recap: Variational Inference

- Functional: a function that maps a function to a value

$$H[p] = \int p(x) \ln p(x) dx$$

- Variational method: find an input function that maximizes the functional
- Variational inference: find a distribution $q(z)$ to approximate $p(Z | X)$ so a functional is maximized

Recap: Variational Inference

$$\ln p(\mathbf{X}) = \mathcal{L}(q) + \text{KL}(q||p)$$

Between $p(\mathbf{Z}|\mathbf{X})$
and $q(\mathbf{Z})$

$$\mathcal{L}(q) = \int q(\mathbf{Z}) \ln \left\{ \frac{p(\mathbf{X}, \mathbf{Z})}{q(\mathbf{Z})} \right\} d\mathbf{Z}$$

$$\text{KL}(q||p) = - \int q(\mathbf{Z}) \ln \left\{ \frac{p(\mathbf{Z}|\mathbf{X})}{q(\mathbf{Z})} \right\} d\mathbf{Z}$$

If q can be any distribution, then variational inference is precise.
But in practice, it cannot

Is the following statement right?

- Probability $p(Z, X)$ is usually easier to evaluate compared to $P(Z | X)$.

Recap: Sampling Methods

- Stochastic methods
- Also called Monte Carlo methods

$$\mathbb{E}[f] = \int f(\mathbf{z})p(\mathbf{z}) d\mathbf{z} \quad \longrightarrow \quad \hat{f} = \frac{1}{L} \sum_{l=1}^L f(\mathbf{z}^{(l)}) \quad \mathbf{z}_1, \dots, \mathbf{z}_L \text{ are samples from } p$$

Recap: Sampling Methods

- Transformation method: $\text{CDF}^{-1}(\text{uniform}(0,1))$
- Rejection sampling
 - A proposal distribution $q(z)$
 - Choose k , such that $k \cdot q(z) \geq p(z)$, for any x
 - Sampling process:
 - Sample z_0 from $q(z)$
 - Sample h from $\text{uniform}(0, k \cdot q(z_0))$
 - If $h > p(z_0)$, discard it; otherwise, keep it

Is the following statement correct?

- All primitive distributions can be constructed using the inverse CDF.

Is the following statement right?

- In rejection sampling, given k , the probability whether a sample is accepted does not depend on the proposal distribution

Is the following statement correct?

- The efficiency of rejection sampling depends on the choice of the proposal distribution

Recap: Sampling Methods

- Importance sampling
 - Used to evaluate $f(z)$ where z is from $p(z)$

$$E(f) = \int f(z)p(z)dz = \int f(z)\frac{p(z)}{q(z)}q(z)dz \approx \frac{1}{L}\sum_{l=1}^L\frac{p(z^l)}{q(z^l)}f(z^l)$$

- How to get real samples: create a new discrete distribution using the above samples and set their probabilities using the importance weights

Recap: Sampling Methods

- Markov Chain Monte Carlo
 - A sampling method that works with a large family of distributions and high dimensions
- Workflow
 - Start with some sample z_0
 - Suppose the current sample is z^τ . Draw next sample z^* from $q(z | z^\tau)$
 - Decide whether to accept z^* as the next state based some criteria. If accepted, $z^{\tau+1} = z^*$. Otherwise, $z^{\tau+1} = z^\tau$
 - Samples form a Markov chain

Recap: Sampling Methods

	Metropolis	Metropolis-Hasting
Constraints on the proposal distribution	Symmetric	None
Accepting probability	$\min(1, \frac{p(z')}{p(z)})$	$\min(1, \frac{p(z')q(z' z)}{p(z)q(z z')})$

Recap: Why MCMC works?

- Markov chain: $p(\mathbf{z}^{(m+1)} | \mathbf{z}^{(1)}, \dots, \mathbf{z}^{(m)}) = p(\mathbf{z}^{(m+1)} | \mathbf{z}^{(m)})$.
- Stationary distribution of a Markov chain: each step in the chain does not change the distribution.

- Detailed balance: $p^*(\mathbf{z})T(\mathbf{z}, \mathbf{z}') = p^*(\mathbf{z}')T(\mathbf{z}', \mathbf{z})$
 - $p^*(\mathbf{z})$ is a stationary distribution
- A *ergodic* Markov chain converges to the same distribution regardless the initial distribution
 - The system does not return to the same state at fixed intervals
 - The expected number of steps for returning to the same state is finite

Is the following statement right?

- The samples drawn using MCMC are independent

Is the following statement right?

- A Markov chain can have more than one stationary distribution

Use MCMC to solve the problem below

- Super optimization
 - There is a straight-line program
 - A set of test cases are given
 - The program can be modified by deleting a statement, inserting a statement from the initial program at a given place
 - Optimize the program by using the above operations

Motivations

- In order to reason about properties of a program, we need formal tools
- Example questions
 - Is the postcondition satisfied?
 - Does this program halt on all inputs?
 - Does it always halt in polynomial time?

Motivations

- In order to reason about properties of a program, we need formal tools
- Example questions
 - What is the probability that the postcondition is satisfied?
 - What is the probability that this program halts on all inputs?
 - What is the probability that it halts in polynomial time?

Motivations

- When designing a language, rigorous semantics is needed to guarantee its correctness
- An example that didn't have rigorous semantics: Javascript
 - <https://javascriptwtf.com>

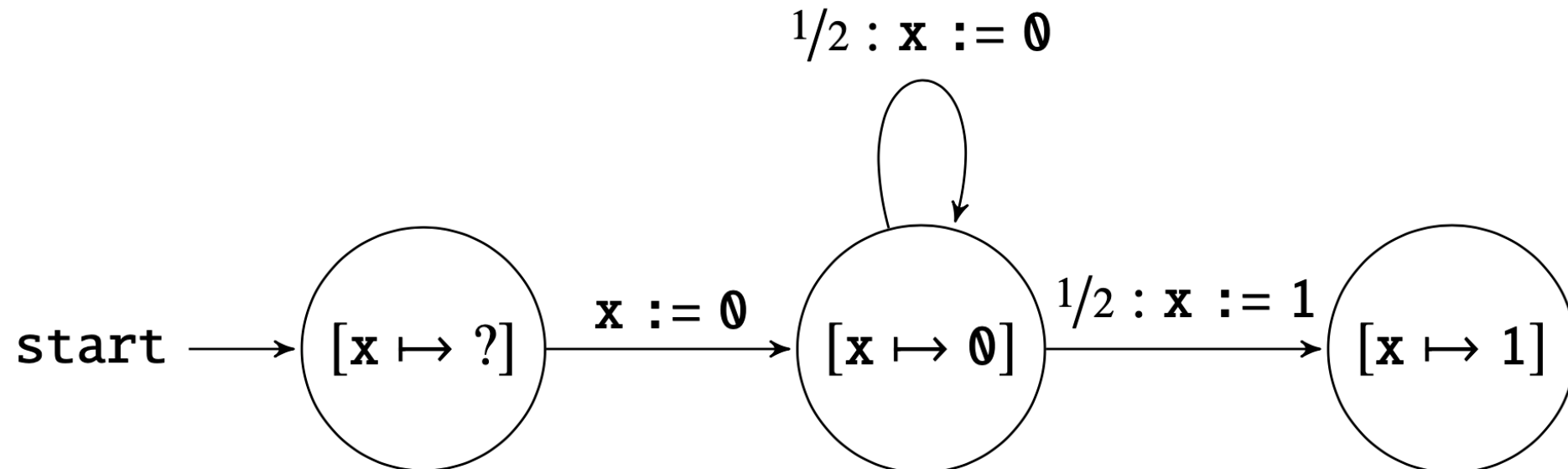
Examples

We can decompose the semantics of a program into semantics of statements

$x := 0$

while $x == 0$ **do**
 $x := \text{coin}()$

What is the probability that It runs through n iterations?
 What is the expected number of iterations?
 What is the probability that the program halts?



Examples

```
main{
    u:=0;
    v:=0;
    step(u,v);
    while u!=0 || v!=0 do
        step(u,v)
}
```

```
step(u,v){
    x:=coin();
    y:=coin();
    u:=u+(x-y);
    v:=v+(x+y-1)
}
```

What is the probability that the program halts?

The program is a two-dimensional random walk. According to probability theory, the probability that it returns to the origin is 1.

By relating to concepts in probabilities, we can simplify the reasoning

Examples

```
i:=0;
n:=0;
while i<1e9 do
    x:=rand();
    y:=rand();
    if (x*x+y*y) < 1 then n:=n+1;
    i:=i+1
i:=4*n/1e9;
```

What does this program compute?

How to reason about it?

Measure Theory

The mathematical foundation of
probabilities and integration

Uniform(0,1) is called a *Lebesgue measure*

This Class

- Syntax of a simple imperative probabilistic language
- Operational semantics
- Measure theory & denotational semantics (brief)

A Simple Imperative Language

- Highly simplified version
- Enough to explain the core concepts

Syntax

- Deterministic terms (expressions)
- Terms (Deterministic + Probabilistic)
- Tests (expression that evaluate to Booleans)
- Programs

Syntax – Deterministic Terms

(i) Deterministic terms:

$d ::= a$

| x

| $d \text{ op } d$

$a \in \mathbb{R}$, constants

$x \in \text{Var}$, a countable set of variables

$\text{op} \in \{+, -, *, \div\}$

Syntax - Terms

(ii) Terms:

$t ::= d$

| **coin()** | **rand()**

| $t \text{ op } t$

d a deterministic term

sample in $\{0, 1\}$ and $[0, 1]$, respectively

$\text{op} \in \{+, -, *, \div\}$

Syntax - Tests

(iii) Tests:

$b ::= \text{true} \mid \text{false}$

$\mid d == d \mid d < d \mid d > d$

$\mid b \ \&\& \ b \mid b \ \|\| \ b \mid !b$

comparison of deterministic terms

Boolean combinations of tests

Syntax - Program

(iv) Programs:

$e ::= \text{skip}$

| $x := t$

| $e ; e$

| $\text{if } b \text{ then } e \text{ else } e$

| $\text{while } b \text{ do } e$

assignment

sequential composition

conditional

while loop

Syntax - Example Program

```
if coin() == 1 then
    x := rand() * 5
else
    x := 6
if x > 4.5 then
    y := coin() + 2
else
    y := 100
```

Operational Semantics

- Model the step-by-step executions of a program on a machine
- Tracks the memory-state
 - Values assigned to each variable
 - Values of each random number generator
 - A stack of instructions

Random Number Generators

- Modeled as infinite streams of numbers:
 - `coin()`: $m_0 m_1 \dots$ are i.i.d from Bernoulli(0.5)
 - `rand()`: $p_0 p_1 \dots$ are i.i.d from uniform(0, 1)
- When invoking the generator, a number is taken from the stream
 - Pseudo-random generators

Operational Semantics: Machine States

- A memory-state is a triple (s, m, p)
 - A store $s: n \rightarrow R$, where there are n variables in the program
 - $m \in \{0,1\}^\omega$ is the current stream of available random Boolean values
 - $p \in [0,1]^\omega$ is the current stream of available random real values
- A machine-state is a 4-tuple (e, s, m, p)
 - e corresponds to a stack of instructions
 - (s, m, p) is a memory-state

Machine States: Example

(e, $\{x \rightarrow \perp\}$, 1001011..., 0.2 0.5 0.9 0.21...)

if **coin()** == 1 **then**

(**x := rand()** * 5, $\{x \rightarrow \perp\}$, 001011..., 0.2 0.5 0.9 0.21...)

x := rand() * 5

(skip, $\{x \rightarrow 1\}$, 001011..., 0.5 0.9 0.21...)

else

x := 6

Operational Semantics: Introduction

- We now talk about how a program modifies the machine state
- Type of the operational semantics
$$(e, s, m, p) \rightarrow (e', s', m', p')$$
- Before talking about the reduction, we need to define semantics of terms and tests

Semantics of Terms

$$\llbracket t \rrbracket : \mathbf{R}^n \times \mathbf{N}^\omega \times \mathbf{R}^\omega \rightarrow \mathbf{R} \times \mathbf{N}^\omega \times \mathbf{R}^\omega$$

$$\llbracket r \rrbracket : (s, m, p) \mapsto (r, m, p)$$

$$\llbracket x_i \rrbracket : (s, m, p) \mapsto (s(i), m, p)$$

$$\llbracket \text{coin}() \rrbracket : (s, m, p) \mapsto (\text{hd } m, \text{tl } m, p)$$

$$\llbracket \text{rand}() \rrbracket : (s, m, p) \mapsto (\text{hd } p, m, \text{tl } p)$$

$$\begin{aligned} \llbracket t_1 \text{ op } t_2 \rrbracket : (s, m, p) \mapsto & \text{ let } (a_1, m', p') = \llbracket t_1 \rrbracket (s, m, p) \text{ in} \\ & \text{ let } (a_2, m'', p'') = \llbracket t_2 \rrbracket (s, m', p') \text{ in} \\ & (a_1 \text{ op } a_2, m'', p'') \end{aligned}$$

$$\text{opn} \in \{+, 0, *, \div\} \text{hd}(m_1 m_2, \dots) = m_1$$

Semantics of Tests

$$\llbracket b \rrbracket : R^n \times N^\omega \times R^\omega \rightarrow \{true, false\}$$

$$\llbracket t_1 == t_2 \rrbracket : (s, m, p) \mapsto \begin{cases} true & \text{if } \llbracket t_1 \rrbracket(s, m, p) = \llbracket t_2 \rrbracket(s, m, p) \\ false & \text{otherwise} \end{cases}$$

$$\llbracket t_1 < t_2 \rrbracket : (s, m, p) \mapsto \begin{cases} true & \text{if } \llbracket t_1 \rrbracket(s, m, p) < \llbracket t_2 \rrbracket(s, m, p) \\ false & \text{otherwise} \end{cases}$$

$$\llbracket t_1 > t_2 \rrbracket : (s, m, p) \mapsto \begin{cases} true & \text{if } \llbracket t_1 \rrbracket(s, m, p) > \llbracket t_2 \rrbracket(s, m, p) \\ false & \text{otherwise} \end{cases}$$

$$\llbracket b_1 \ \&\& \ b_2 \rrbracket : (s, m, p) \mapsto \llbracket b_1 \rrbracket(s, m, p) \wedge \llbracket b_2 \rrbracket(s, m, p)$$

$$\llbracket b_1 \ || \ b_2 \rrbracket : (s, m, p) \mapsto \llbracket b_1 \rrbracket(s, m, p) \vee \llbracket b_2 \rrbracket(s, m, p)$$

$$\llbracket !b \rrbracket : (s, m, p) \mapsto \neg \llbracket b \rrbracket(s, m, p)$$

Operational Semantics: Reduction

Assignment:

$$\frac{\llbracket t \rrbracket(s, m, p) = (a, m', p')}{(x_i := t, s, m, p) \longrightarrow (\text{skip}, s[i \mapsto a], m', p')}$$

Sequential composition:

$$\frac{(e_1, s, m, p) \longrightarrow (e'_1, s', m', p')}{(e_1 ; e_2, s, m, p) \longrightarrow (e'_1 ; e_2, s', m', p')} \quad \frac{}{(\text{skip} ; e, s, m, p) \longrightarrow (e, s, m, p)}$$

Operational Semantics: Reduction

Conditional:

$$\frac{\llbracket b \rrbracket(s, m, p) = \text{true}}{(\text{if } b \text{ then } e_1 \text{ else } e_2, s, m, p) \longrightarrow (e_1, s, m, p)}$$

$$\frac{\llbracket b \rrbracket(s, m, p) = \text{false}}{(\text{if } b \text{ then } e_1 \text{ else } e_2, s, m, p) \longrightarrow (e_2, s, m, p)}$$

while loops:

$$\frac{}{(\text{while } b \text{ do } e, s, m, p) \longrightarrow (\text{if } b \text{ then } (e ; \text{while } b \text{ do } e) \text{ else skip}, s, m, p)}$$

Operational Semantics: Reduction

Reflexive-transitive closure:

$$\begin{array}{c}
 \hline
 (e, s, m, p) \xrightarrow{*} (e, s, m, p)
 \end{array}
 \qquad
 \begin{array}{c}
 (e_1, s_1, m_1, p_1) \longrightarrow (e_2, s_2, m_2, p_2) \\
 \hline
 (e_1, s_1, m_1, p_1) \xrightarrow{*} (e_2, s_2, m_2, p_2)
 \end{array}$$

$$\begin{array}{c}
 (e_1, s_1, m_1, p_1) \xrightarrow{*} (e_2, s_2, m_2, p_2) \qquad (e_2, s_2, m_2, p_2) \xrightarrow{*} (e_3, s_3, m_3, p_3) \\
 \hline
 (e_1, s_1, m_1, p_1) \xrightarrow{*} (e_3, s_3, m_3, p_3)
 \end{array}$$

Operational Semantics: Termination

- A program e terminates from (s, m, p) if

$$(e, s, m, p) \xrightarrow{*} (\mathbf{skip}, s', m', p').$$

- We say e diverges from (s, m, p) if it does not terminate

Operational Semantics: Examples

x := 0

while x == 0 **do**
 x := **coin()**

What is the probability that the program halts?

$$(x := 0, s, m, p) \longrightarrow (\text{skip}, s[x \mapsto 0], m, p)$$

$$\frac{(x := 0 ; e, s, m, p) \longrightarrow (\text{skip} ; e, s[x \mapsto 0], m, p)}{\quad} \quad \frac{(\text{skip} ; e, s[x \mapsto 0], m, p) \longrightarrow (e, s[x \mapsto 0], m, p)}{\quad}$$

$$\frac{(x := 0 ; e, s, m, p) \xrightarrow{*} (\text{skip} ; e, s[x \mapsto 0], m, p) \quad (\text{skip} ; e, s[x \mapsto 0], m, p) \xrightarrow{*} (e, s[x \mapsto 0], m, p)}{\quad}$$

$$(x := 0 ; e, s, m, p) \xrightarrow{*} (e, s[x \mapsto 0], m, p)$$

Operational Semantics: Examples

$x := 0$

while $x == 0$ **do**
 $x := \text{coin}()$

What is the probability that the program halts?

$$(x := 0 ; e, s, m, p) \xrightarrow{*} (e, s[x \mapsto 0], m, p)$$

$$(e, s[x \mapsto 0], m, p) \xrightarrow{*} (x := \text{coin}() ; e, s[x \mapsto 0], m, p)$$

$$(\text{while } b \text{ do } e, s, m, p) \longrightarrow (\text{if } b \text{ then } (e ; \text{while } b \text{ do } e) \text{ else skip}, s, m, p)$$

$$\frac{[[b]](s, m, p) = \text{true}}{(\text{if } b \text{ then } e_1 \text{ else } e_2, s, m, p) \longrightarrow (e_1, s, m, p)}$$

Operational Semantics: Examples

```
x := 0
while x == 0 do
  x := coin()
```

What is the probability that the program halts?

$$(x := 0 ; e, s, m, p) \xrightarrow{*} (e, s[x \mapsto 0], m, p)$$

$$(e, s[x \mapsto 0], m, p) \xrightarrow{*} (x := \text{coin}() ; e, s[x \mapsto 0], m, p)$$

$$(x := \text{coin}() ; e, s[x \mapsto 0], m, p) \xrightarrow{*} (e, [s \mapsto \text{hd } m], \text{tl } m, p). \quad \begin{array}{l} \text{hd}(m_1 m_2 \dots) = m_1 \\ \text{tl}(m_1 m_2 \dots) = m_2 \dots \end{array}$$

The loop continues until it reaches m in the form of $1m'$

$$(e, s[x \mapsto 1], m', p) \xrightarrow{*} (\text{skip}, s[x \mapsto 1], m', p)$$

$$(x := 0 ; e, s, m, p) \xrightarrow{*} (\text{skip}, s[x \mapsto 1], m', p)$$

Operational Semantics: Examples

$$\begin{aligned}
 & \mathbb{P} \left[\exists m' (x := 0 ; e, s, m, p) \xrightarrow{*} (\text{skip}, s[x \mapsto 1], m', p) \right] \\
 &= \mathbb{P} \left[\exists k \geq 0 \exists m' m = 0^k 1 m' \right] \\
 &= \sum_{k=1}^{\infty} 2^{-k} = 1
 \end{aligned}$$

Operational Semantics: Examples

```

main{
  u:=0;
  v:=0;
  step(u,v);
  while u!=0 || v!=0 do
    step(u,v)
}

step(u,v){
  x:=coin();
  y:=coin();
  u:=u+(x-y);
  v:=v+(x+y-1)
}

```

What is the probability that the program halts?

$$(\text{step}, s, 00m, p) \xrightarrow{*} (\text{skip}, s[(u, v) \mapsto (0, -1), (x, y) \mapsto (0, 0)], m, p)$$

$$(\text{step}, s, 01m, p) \xrightarrow{*} (\text{skip}, s[(u, v) \mapsto (-1, 0), (x, y) \mapsto (0, 1)], m, p)$$

$$(\text{step}, s, 10m, p) \xrightarrow{*} (\text{skip}, s[(u, v) \mapsto (1, 0), (x, y) \mapsto (1, 0)], m, p)$$

$$(\text{step}, s, 11m, p) \xrightarrow{*} (\text{skip}, s[(u, v) \mapsto (0, 1), (x, y) \mapsto (1, 1)], m, p)$$

Operational Semantics: Examples

```

main{
  u:=0;
  v:=0;
  step(u,v);
  while u!=0 || v!=0 do
    step(u,v)
}

```

What is the probability that the program halts?

We define i.i.d variables $X_1, X_2 \dots$ on Z^2 such that
 $X_i \in \{(0,1), (0,-1), (1,0), (-1,0)\}$

$$S_n = \sum_{i=1}^n X_i$$

```

step(u,v){
  x:=coin();
  y:=coin();
  u:=u+(x-y);
  v:=v+(x+y-1)
}

```

$(\text{main}, s, m, p) \xrightarrow{*}$

$(\text{while } !(u == 0) \parallel !(v == 0) \text{ do step}(u, v), s[(u, v) \mapsto (i, j)], \text{tl}^4(m), p)$

Operational Semantics: Examples

```

main{
  u:=0;
  v:=0;
  step(u,v);
  while u!=0 || v!=0 do
    step(u,v)
}

```

What is the probability that the program halts?

The program halts if $\exists n. S_{2n} = (0,0)$

$(\text{main}, s, m, p) \xrightarrow{*} (\text{skip}, s[(u, v) \mapsto (0, 0)], t^{4n}(m), p).$

```

step(u,v){
  x:=coin();
  y:=coin();
  u:=u+(x-y);
  v:=v+(x+y-1)
}

```

$$\begin{aligned}
 & \mathbb{P} \left[\exists n (\text{main}, s, m, p) \xrightarrow{*} (\text{skip}, s[(u, v) \mapsto (0, 0)], t^{4n}(m), p) \right] \\
 &= \mathbb{P} \left[\bigvee_{n=0}^{\infty} S_{2n} = (0, 0) \right]
 \end{aligned}$$

Operational Semantics: Examples

```

main{
    u:=0;
    v:=0;
    step(u,v);
    while u!=0 || v!=0 do
        step(u,v)
}

step(u,v){
    x:=coin();
    y:=coin();
    u:=u+(x-y);
    v:=v+(x+y-1)
}

```

What is the probability that the program halts?

$$\begin{aligned}
 \mathbb{P}[S_{2n} = (0, 0)] &= 4^{-2n} \sum_{m=0}^n \frac{(2n)!}{m!m!(n-m)!(n-m)!} \\
 &= 4^{-2n} \binom{2n}{n} \sum_{m=0}^n \binom{n}{m}^2 \\
 &= 4^{-2n} \binom{2n}{n}^2.
 \end{aligned}$$

Operational Semantics: Examples

$i:=0;$

$n:=0;$

while $i < 1e9$ **do**

$x:=\text{rand}();$

$y:=\text{rand}();$

if $(x*x+y*y) < 1$

then $n:=n+1;$

$i:=i+1$

$i:=4*n/1e9;$

Given $\epsilon > 0$, what is $P(|i - \pi| \leq \epsilon)$?

$(\text{prog}, s, m, p) \xrightarrow{*} (\text{skip}, s[\mathbf{i} \mapsto 4n/N, \mathbf{n} \mapsto n, \dots], m, \text{tl}^{2N}(p))$

n/N is the expectation of

$$Z = \begin{cases} 1 & \text{if } X^2 + Y^2 < 1 \\ 0 & \text{else} \end{cases}$$

Operational Semantics: Examples

$i:=0;$

$n:=0;$

while $i < 1e9$ **do**

$x:=\text{rand}();$

$y:=\text{rand}();$

if $(x*x+y*y) < 1$

then $n:=n+1;$

$i:=i+1$

$i:=4*n/1e9;$

Given $\epsilon > 0$, what is $P(|i - \pi| \leq \epsilon)$?

n/N is the expectation of $Z = \begin{cases} 1 & \text{if } X^2 + Y^2 < 1 \\ 0 & \text{else} \end{cases}$

$$\mathbb{P}[X^2 \leq t] = \mathbb{P}[X \leq \sqrt{t}] = \int_0^{\sqrt{t}} \mathbb{1}_{[0,1]}(x) dx = \sqrt{t}$$

$$f(t) = \frac{\partial \mathbb{P}[X^2 \leq t]}{\partial t} = \frac{1}{2\sqrt{t}} \mathbb{1}_{[0,1]}(t)$$

Operational Semantics: Examples

```

i:=0;
n:=0;
while i<1e9 do
  x:=rand();
  y:=rand();
  if (x*x+y*y) < 1
    then n:=n+1;
  i:=i+1
i:=4*n/1e9;

```

Given $\epsilon > 0$, what is $P(|i - \pi| \leq \epsilon)$?

n/N is the expectation of $Z = \begin{cases} 1 & \text{if } X^2 + Y^2 < 1 \\ 0 & \text{else} \end{cases}$

The density of $X^2 + Y^2$ is

$$\begin{aligned}
 (f * f)(t) &= \int_{-\infty}^{\infty} \frac{1}{2\sqrt{x}} \mathbb{1}_{[0,1]}(x) \frac{1}{2\sqrt{t-x}} \mathbb{1}_{[0,1]}(t-x) dx \\
 &= \begin{cases} \int_0^t \frac{1}{4\sqrt{x}\sqrt{t-x}} dx & \text{if } 0 \leq t \leq 1 \\ \int_{t-1}^1 \frac{1}{4\sqrt{x}\sqrt{t-x}} dx & \text{if } 1 < t \leq 2 \end{cases}
 \end{aligned}$$

Operational Semantics: Examples

$i:=0;$

$n:=0;$

while $i < 1e9$ **do**

$x:=\text{rand}();$

$y:=\text{rand}();$

if $(x*x+y*y) < 1$

then $n:=n+1;$

$i:=i+1$

$i:=4*n/1e9;$

Given $\epsilon > 0$, what is $P(|i - \pi| \leq \epsilon)$?

n/N is the expectation of $Z = \begin{cases} 1 & \text{if } X^2 + Y^2 < 1 \\ 0 & \text{else} \end{cases}$

$\text{exp}(Z)$ is

$$\int_0^t \frac{1}{4\sqrt{x}\sqrt{t-x}} dx = \int_0^1 \frac{1}{2\sqrt{1-u^2}} du = \frac{1}{2}(\sin^{-1}(1) - \sin^{-1}(0)) = \frac{\pi}{4}.$$

$$\mathbb{P}[X^2 + Y^2 \leq 1] = \int_0^1 (f * f)(t) dt = \int_0^1 \frac{\pi}{4} dt = \frac{\pi}{4}.$$

Operational Semantics: Examples

$i:=0;$

$n:=0;$

while $i < 1e9$ **do**

$x:=\text{rand}();$

$y:=\text{rand}();$

if $(x*x+y*y) < 1$

then $n:=n+1;$

$i:=i+1$

endwhile $i:=4*n/1e9;$

Given $\epsilon > 0$, what is $P(|i - \pi| \leq \epsilon)$?

n/N is the expectation of $Z = \begin{cases} 1 & \text{if } X^2 + Y^2 < 1 \\ 0 & \text{else} \end{cases}$

$$\mathbb{P}[X^2 + Y^2 \leq 1] = \int_0^1 (f * f)(t) dt = \int_0^1 \frac{\pi}{4} dt = \frac{\pi}{4}.$$

$$\mathbb{P}\left[\left|\frac{n}{N} - \frac{\pi}{4}\right| > \epsilon\right] \leq \frac{\sigma^2}{N\epsilon^2}. \text{ Where } \sigma^2 = \frac{\pi}{4} - \left(\frac{\pi}{4}\right)^2$$

Chebyshev's
inequality

This Class

- Syntax of a simple imperative probabilistic language
- Operational semantics
- **Measure theory & denotational semantics (brief)**

Denotational vs. Operational Semantics

- Consider $x := \text{coin}()$, in operational semantics:

$$(x := \text{coin}(), s, m, p) \longrightarrow (\text{skip}, s[x \mapsto 0], \text{tl } m, p)$$

$$(x := \text{coin}(), s, m, p) \longrightarrow (\text{skip}, s[x \mapsto 1], \text{tl } m, p)$$

- Denotational semantics:
 - Model all possible executions together
 - States: probability distribution over memory states
 - $\frac{1}{2}s[x \mapsto 0] + \frac{1}{2}s[x \mapsto 1]$

Denotational Semantics: Introduction

- State s can be identified with the Dirac measure σ_s , then the semantics of $x := \text{coin}()$ can be viewed as $\sigma_s \rightarrow \frac{1}{2} s[x \mapsto 0] + \frac{1}{2} s[x \mapsto 1]$
- In general, a program is interpreted as an operator mapping probability distributions to (sub)probability distributions

Denotational Semantics: Definition

- Assume there are n real variables, then a state is a distribution on R^n
- A program $e: MR^n \rightarrow MR^n$
 - An operator called a state transformer

Measure Theory

- Measures: generalization of concepts like length, area, or volume

Measure Example: Length

- What subsets of \mathbb{R} can meaningfully be assigned a length?
- What properties should the length function l satisfy?

Measure Example: Length

$$\ell([a_1, b_1] \cup [a_2, b_2]) = \ell([a_1, b_1]) + \ell([a_2, b_2]) = (b_1 - a_1) + (b_2 - a_2). \quad b_1 < a_2$$

$$\ell\left(\bigcup_{i=1}^n A_i\right) = \sum_{i=1}^n \ell(A_i). \quad A_i \text{ and } A_j \text{ are disjoint. } \ell \text{ is called additive}$$

$$\ell\left(\bigcup_{i=0}^{\infty} A_i\right) = \sum_{i=0}^{\infty} \ell(A_i). \quad A_i \text{ and } A_j \text{ are disjoint. The set is countable. } \ell \text{ is called countably additive or } \sigma\text{-additive}$$

$l(\mathbb{R}) = \infty$, but we are only going to talk about finite measures

$$\ell(B \setminus A) = \ell(B) - \ell(A) \quad \text{Domain should be closed under complementation}$$

Measure Example: Length

- Can we extend the domain of length l to all subsets of \mathbb{R} ?
- No. Counterexample: Vitali sets
 - $V \subseteq [0,1]$, such that for each real number r , there exists exactly one number $v \in V$ such that $v - r$ is rational
 - Let q_1, q_2, \dots be the rational numbers in $[-1,1]$, construct sets $V_k = V + q_k$
 - $[0,1] \subseteq \bigcup_k V_k \subseteq [-1,2]$
 - $l(V_k) = l(V)$, and there are infinitely many V_k
- l is called the *Lebesgue measure* on real numbers

Measurable Spaces and Measures

- (\mathbf{S}, \mathbf{B}) is a measurable space
 - \mathbf{S} is a set
 - \mathbf{B} is a σ -algebra on \mathbf{S} , which is a collection of subsets of \mathbf{S}
 - It contains \emptyset
 - Closed under complementation in \mathbf{S}
 - Closed under countable union
 - The elements of \mathbf{B} are called measurable sets
- If \mathbf{F} is a collection of subsets of \mathbf{S} , $\sigma(\mathbf{F})$ is the smallest σ -algebra containing \mathbf{F} , or $\sigma(\mathcal{F}) \triangleq \bigcap \{ \mathcal{A} \mid \mathcal{F} \subseteq \mathcal{A} \text{ and } \mathcal{A} \text{ is a } \sigma\text{-algebra} \}$. We say $(\mathbf{S}, \sigma(\mathbf{F}))$ is generated by \mathbf{F} .

Measurable Functions

- (S, \mathcal{B}_S) and (T, \mathcal{B}_T) are measurable spaces. A function $f: S \rightarrow T$ is measurable if $f^{-1}(B) = \{x \in S \mid f(x) \in B\}$ for every $B \in \mathcal{B}_T$ is a measurable subset of S

Example:
$$\chi_B(s) = \begin{cases} 1, & s \in B, \\ 0, & s \notin B. \end{cases}$$

Measures: Definitions

- A signed (finite) measure on (\mathbf{S}, \mathbf{B}) is a countably additive map $\mu: \mathbf{B} \rightarrow \mathbf{R}$ such that $\mu(\emptyset) = 0$
- Positive signed measure: $\mu(A) \geq 0$ for all $A \in \mathbf{B}$
- A positive measure is a probability measure if $\mu(S) = 1$
- ...is a subprobability measure if $\mu(S) \leq 1$

Measures: Definitions

- If $\mu(B) = 0$, then B is a μ -nullset
- A property is said to hold μ -almost surely (everywhere) if the sets of points on which it does not hold is contained in nullset
- In probability theory, measures are sometimes called distributions

Measures: Discrete Measures

- For $s \in S$, the Dirac measure, or Dirac delta, or point mass on s :

$$\delta_s(B) = \begin{cases} 1, & s \in B, \\ 0, & s \notin B. \end{cases}$$

- A measure is discrete if it is a countable weighted sum of Dirac measures
 - If the weights add up to one, then it is a discrete probability measure
- Continuous measure: $\mu(\{s\}) = 0$ for all singleton sets $\{s\}$ in \mathbf{B} of (\mathbf{S}, \mathbf{B})

Measures: Pushforward Measure and Lebesgue Integration

- Given $f: (\mathbf{S}, \mathbf{B}_\mathbf{S}) \rightarrow (\mathbf{T}, \mathbf{B}_\mathbf{T})$ measurable, and a measure μ on $\mathbf{B}_\mathbf{S}$, the **pushforward measure** $\mu(f^{-1}(B))$ on $\mathbf{B}_\mathbf{T}$ is defined as

$$f_*(\mu)(B) = \mu(f^{-1}(B)), \quad B \in \mathcal{B}_T.$$

- **Lebesgue integration:** given (\mathbf{S}, \mathbf{B}) , $\mu: \mathbf{B} \rightarrow \mathbf{R}$, $f: \mathbf{S} \rightarrow \mathbf{R}$, where $m < f < M$

$$\int f d\mu = \lim_{n \rightarrow \max} \sum_{i=0}^n f(s_i) \mu(B_i)$$

where B_0, \dots, B_n is a measurable partition of \mathbf{S} , and the value of f does not vary more than $(M - m)/n$ in any B_i and $s_i \in B_i$

Markov Kernels

- Given $(\mathbf{S}, \mathbf{B}_\mathbf{S})$ and $(\mathbf{T}, \mathbf{B}_\mathbf{T})$, $P: \mathbf{S} \times \mathbf{B}_\mathbf{T} \rightarrow \mathbf{R}$ is called a Markov kernel if
 - For fixed $A \in \mathbf{B}_\mathbf{T}$, the map $\lambda s. P(s, A) \rightarrow \mathbf{R}$ is a measurable function on $(\mathbf{S}, \mathbf{B}_\mathbf{S})$
 - For fixed $s \in \mathbf{S}$, the map $\lambda A. P(s, A) \rightarrow \mathbf{R}$ is a probability measure on $(\mathbf{T}, \mathbf{B}_\mathbf{T})$
- Composition of two Markov kernels
 - Given $P: \mathbf{S} \rightarrow \mathbf{T}$, $Q: \mathbf{T} \rightarrow \mathbf{U}$ $(P ; Q)(s, A) = \int_{t \in \mathbf{T}} P(s, dt) \cdot Q(t, A)$.
- Given μ on $\mathbf{B}_\mathbf{S}$, its push forward under the Markov Kernel P is

$$P_*(\mu)(B) = \int_{s \in \mathbf{S}} P(s, B) \mu(ds).$$

More on Markov Kernels

- (S, B_S) : $x = \dots$ ($x > 0$)
- (T, B_T) : $y = \text{uniform}(0, x)$
- Markov kernel $P(x, \cup_{i=1}^{i=M} [a_i, b_i]) = \sum_{i=1}^{i=M} \text{length}([a_i, b_i] \cap [0, x]) / x$

More on Markov Kernels

- (S, B_S) : $x = \dots$ ($x > 0$)
- (O, B_O) : $y = \text{uniform}(0, x)$
- (T, B_T) : $z = \text{uniform}(0, y)$
- Composition: $(P; Q)(x, [0, z]) = \int_{y \in [0, \infty]} P(x, dy) * Q(y, [0, z])$
 $z < x$

$$= \int_{y \in [0, x]} \frac{dy}{x} * \frac{\text{length}([0, z] \cap [0, y])}{y}$$

$$= \int_{y \in [0, z]} \frac{dy}{x} * \frac{y}{y} + \int_{y \in [z, x]} \frac{dy}{x} * \frac{z}{y} = \frac{z}{x} + \frac{z}{x} (\ln x - \ln z)$$

More on Markov Kernels

- $(\mathcal{S}, \mathbf{B}_{\mathcal{S}})$: $x = \text{uniform}(0.1, 1.1)$ $\mu([a, b]) = \text{length}([a, b] \cap [0.1, 1.1])$
- $(\mathcal{T}, \mathbf{B}_{\mathcal{T}})$: $y = \text{uniform}(0, x)$
- Markov kernel $P(x, \cup_{i=1}^M [a_i, b_i]) = \sum_{i=1}^M \text{length}([a_i, b_i] \cap [0, x]) / x$
- μ 's pushforward under P is

$$P_*(\mu)(B_{\mathcal{T}}) = \int_{x \in [0.1, 1.1]} B_{\mathcal{T}} \cap [0, x] * \mu(dx)$$

More on Markov Kernels

- We can use Markov kernels to define the meanings of statements
- A term can be seen as a Markov kernel that links the input variables (can be a distribution) with the output distribution

Summary

- To reason about properties and correctness of probabilistic programs, we need semantics
- To define semantics, we can
 - Decompose it into semantics of program structures
 - Link it with mathematical concepts